

Three Examples of Multi-agent Systems Research

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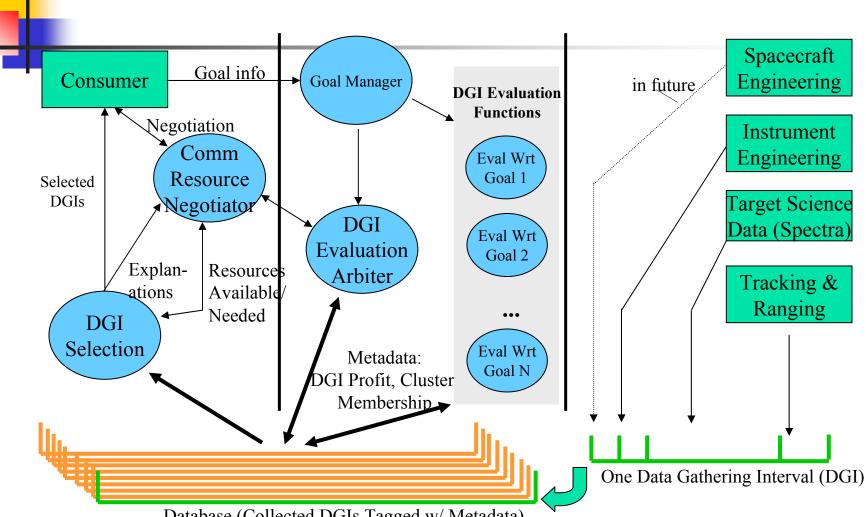




- The purpose of the multi-agent research is to more clearly understand the applicability of this technology in different domains. Currently we are considering:
 - Progressive Autonomy
 – a multi-agent system supporting progressive autonomy for ground-based and/or on-board spectral data processing
 - Autonomic Systems a multi-agent system approach for realizing autonomic properties in mission operations systems
 - Electronic Training a multi-agent system providing an intelligent interface for student monitoring and tutorial text management

Spectral Analysis Automation - SAA

Spectral Analysis Automation / Data Filtering Architecture



Three Examples of Multi-agent Systems (Collected DGIs Tagged w/ Metadata)

Research

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- A prototype of the SAA has been developed.
 - The testbed for the prototype is the library of spectral images from the NEAR spacecraft
- The study of a future testbed consisting of a community of robotic devices for lunar exploration is commencing.
- A study of progressive autonomy, based on SAA ideas, has commenced



■'A System S is autonomic if:

- it has knowledge of itself, in terms of resources and capabilities
- it has the ability to configure and reconfigure itself
- it has the ability to continuously self-optimize itself
- it has self-healing capabilities
- it has self-protection capabilities
- it has the ability to discover knowledge of its environment and context and adapt accordingly
- it has the ability to function in a heterogeneous environment
- it has the ability to anticipate and adapt to user needs



Autonomic Computing (Cont'd)

Current Status:

- Have entered into a collaborative agreement with IBM and GMSEC to investigate the applicability of autonomic principles in ground control systems
- Have developed, with the support of WPI students, a prototype demonstrating selected autonomic capabilities
- Have commenced discussions with IBM Research on the application of autonomic capabilities in fault detection and isolation systems

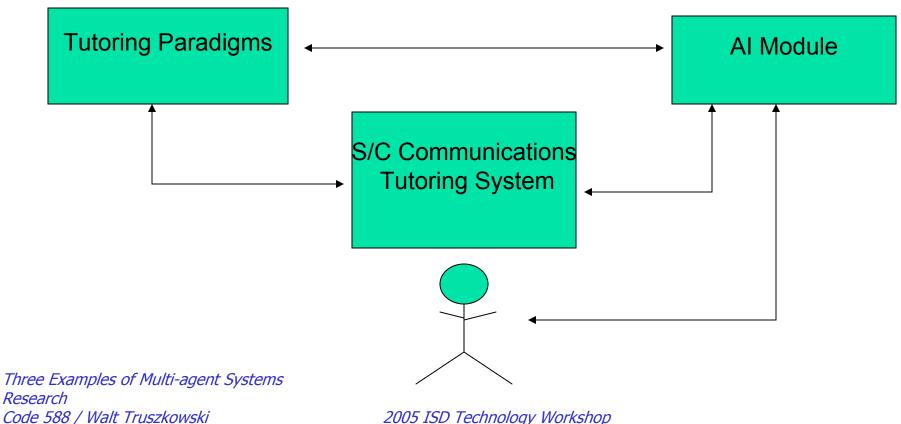


Autonomic Computing (Cont'd)

Work will continue with IBM for the possible application of autonomic system principles to both GMSEC ground system infrastructure and operations and for fault detection and isolation systems.

Web-based Intelligent Tutoring System (WITS)

Four major components of WITS





Web-based Intelligent Tutoring System (WITS) (Cont'd)

- Work on the development of WITS, in conjunction with Southeastern University (SEU) in Washington, DC, has just commenced.
 - Focus of the WITS will be ground/spacecraft communications